# Modeling of Lithuanian parliamentary elections using ABM

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### Empirical analysis

A. Kononovicius LT elections and ABM

### The Lithuanian parliamentary election system

#### Basic facts:

- Elections are being held each 4 years.
- All of the 141 seats are being contested.
- 71 electoral districts.
- Two-tier voting system:
  - District representative
  - Open party list



Elected district representatives by party (colors) in 2008 elections

Image source: screenshot of http://rinkimurezultatai.lt/

### Example ballots



#### We analyze

- voting for major parties (their lists) in 1992, 2008, 2012 elections.
- results at the smallest scale available (polling stations).

Image source: Central Electoral Commission

#### Freely available from:

- Central Electoral Commission: https://rinkejopuslapis.lt
- Baltic Institute of Advanced Technology: http://rinkimurezultatai.lt
- My github repository: https://github.com/akononovicius/lithuanianparliamentary-election-data



#### 1992 election results I Vote-share PDF



Vote-share PDF (gray curve) of four parties with average vote-share above 5% (a)-(c) and all other smaller parties combined (d). Fits (red curve) are provided assuming Beta distribution.

### 1992 election results II

Vote-share rank-size distribution



Rank-size distribution (gray curve) of four parties with average voteshare above 5% (a)-(c) and all other smaller parties combined (d). Fits (red curve) are provided assuming Beta distribution.



All outliers are present in vote-share data of a single party, which represents Lithuanian ethnic minorities (darker curve), while other small parties have no outliers (brighter curve). Fit (red curve) is provided assuming a mixture of two Beta distributions, fit (blue curve) is provided assuming Beta distribution.

Similar observation made in T. Fenner et al., arXiv:1609.04282 [physics.soc-ph].

#### Beta distribution and oft-used alternatives



Comparison of Weibull ( $\lambda = 0.25$ , k = 4), Gaussian ( $\mu = 0.23$  and  $\sigma = 0.065$ ) and Beta ( $\varepsilon_1 = 9.5$ ,  $\varepsilon_2 = 30.5$ ) distributions.

R. F. da Paz et al., Springer Proc Math Stat, 2015.

J. Fernndez-Gracia et al., Phys Rev Lett 112, 2013.

#### 2008 election results I Vote-share PDF



Vote-share distribution (gray curve) of seven parties with average vote-share above 5% (a)-(g) and all other smaller parties combined (h). Fits (red curve) are provided assuming a mixture of two Beta distributions.

### 2008 election results II

Vote-share rank-size distribution



Rank-size distribution (gray curve) of seven parties with average voteshare above 5% (a)-(g) and all other smaller parties combined (h). Fits (red curve) are provided assuming a mixture of two Beta distributions.

#### 2012 election results I Vote-share PDF



Vote-share distribution (gray curve) of seven parties with average vote-share above 5% (a)-(g) and all other smaller parties combined (h). Fits (red curve) are provided assuming a mixture of two Beta distributions.

### 2012 election results II

Vote-share rank-size distribution



Rank-size distribution (gray curve) of seven parties with average voteshare above 5% (a)-(g) and all other smaller parties combined (h). Fits (red curve) are provided assuming a mixture of two Beta distributions.

### Agent-based model of imitative voting

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#### Imitative (herding) behavior in social insects





Upper image taken from Detrain & Deneubourg, PLR 3 (2006)

#### Formulation of the two-state model

- Pick one random agent.
- If agent is "red", then agent switches to "blue" with probability

$$P_{r \to b} = [\varepsilon_b + (N - X)]h\Delta t,$$

otherwise the agent is "blue", the switching probability to "red" is

$$P_{b\to r} = [\varepsilon_r + \mathbf{X}]h\Delta t.$$

Stationary distribution of x = X/N is Beta,

$$p(x) \propto x^{\varepsilon_r - 1} (1 - x)^{\varepsilon_b - 1}.$$

Kirman, QJE 108, 137-156 (1993)

#### Formulation of the M-state model

- Pick a random agent.
- If agent votes for *i* party, the probability to switch to any other party is given by:

$$P_{i} = \sum_{j \neq i} \left[ \varepsilon_{j} + X_{j} \right] h\Delta t = \left[ \varepsilon_{-i} + (N - X_{i}) \right] h\Delta t$$

If agent decides to switch, the party is picked proportionaly based on P˜<sub>i,j</sub> ∝ ε<sub>j</sub> + X<sub>j</sub>.

Should be equivalent to a noisy multi-state Voter model.

#### Illustration of the three-state case



$$P_A = [\varepsilon_{-A} + (N - X_A)] h\Delta t = [\varepsilon_B + X_B + \varepsilon_C + X_C] h\Delta t = \tilde{P}_{A,B} + \tilde{P}_{A,C}.$$

Due to similarity to the two-state model, we expect that each  $x_i = X_i/N$  is distributed according to Beta distribution with parameters  $\varepsilon_i$  and  $\varepsilon_{-i}$ .

Thus stationary distribution of vote-share vector,  $\vec{x} = \{x_1, \ldots, x_M\}$ , should be Dirichlet distribution:

$$p(\vec{x}) \propto \prod_{i=1}^{M} x_i^{\varepsilon_i - 1}.$$

### Reproducing results of 1992 elections

A. Kononovicius LT elections and ABM

### Modeling implications and the actual data

Party	$\hat{\varepsilon}_i$	$\hat{\varepsilon}_{-i}$	$R^2_{PDF}$	$R^2_{RS}$
SK	3.9	16.6	0.95	0.994
LKDP	2.2	16	0.92	0.995
LDDP	5.7	6.1	0.91	0.998
Other	3.3	14.4	0.91	0.86
	15.1			

A restriction follows from the model:

$$\varepsilon_{-i} = \sum_{j=1}^{M} \varepsilon_j - \varepsilon_i,$$

which does not hold for the data. Over-fitting?

### Bayesian inference of $\varepsilon_i$

We split data of 1992 elections into two sets:

- minority party vote share > 20% (94 polling stations),
- minority party vote share < 20% (1966 polling stations).

> :	20%	polling	stations
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Party	$\varepsilon_i$	
SK	$0.65\pm0.1$	
LKDP	$0.35\pm0.05$	
LDDP	$2.5\pm0.2$	
Other	$4.7\pm0.4$	
	8.2	

<20% polling stations

Party	$\varepsilon_i$	
SK	$3.8 \pm 0.1$	
LKDP	$2.55\pm0.1$	
LDDP	$9.3 \pm 0.2$	
Other	$3.7 \pm 0.1$	
	19.35	

### Reproducing 1992 elections



Vote-share PDF of the three main parties (a)-(c) and the other party (d).



Rank-size distribution of the three main parties (a)-(c) and the other party (d).

### To summarize...

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- We have shown that vote-share distributions are well approximated by a mixture of two Beta distributions.
- We have presented a simple model, which reproduces Beta and, more generally, Dirichlet distribution.
- We have used Bayesian inference to infer model parameters from the 1992 election results.
- We have used the inferred parameters to reproduce the 1992 election results.

A. Kononovicius, arXiv:1704.02101 [physics.soc-ph]

## Thank You!



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