

3. Special Relativity (SR) — Examples

Example 1: going into a restframe by a Lorentz transformation (LT)

- we see a particle (or a train, or ...) moving with the speed v in \hat{x} direction
 - for simplicity we suppress \hat{y} and \hat{z} directions \Rightarrow only two component vectors
 - the velocity between our frame O and the particles restframe O' is $\vec{v} = v \hat{x}$
 - the LT $O \rightarrow O'$ is given by $\vec{\beta} = \frac{\vec{v}}{c}$: $\Lambda = \begin{pmatrix} \gamma & -\gamma\beta \\ -\gamma\beta & \gamma \end{pmatrix}$
 - the LT $O' \rightarrow O$ is given by $\vec{\beta}' = \frac{\vec{v}'}{c} = -\frac{\vec{v}}{c}$: $\Lambda' = \begin{pmatrix} \gamma & \gamma\beta \\ \gamma\beta & \gamma \end{pmatrix}$
 - the **four momentum** of the particle in O' (its **restframe** !) is $p'^{\mu} = \begin{pmatrix} m \\ \vec{0} \end{pmatrix}$
 - * its **mass** m is the **energy** of the **four momentum** in its **restframe**
 - the **four momentum** in O is $p^{\mu} = \Lambda'^{\mu}_{\nu} p'^{\nu}$ or

$$p^{\mu} = \begin{pmatrix} E \\ \vec{p} \end{pmatrix} = \begin{pmatrix} \gamma & \gamma\vec{\beta} \\ \gamma\vec{\beta} & \gamma \end{pmatrix} \cdot \begin{pmatrix} m \\ \vec{0} \end{pmatrix} = \begin{pmatrix} m\gamma \\ m\gamma\vec{\beta} \end{pmatrix} \Rightarrow \begin{cases} E = m\gamma \\ \vec{p} = m\gamma\vec{\beta} \end{cases}$$
- solving these equations for the velocity $\vec{v} = \vec{\beta}c$ gives $\vec{v} = \frac{\vec{p}}{E}c$

3. Special Relativity (SR) — Examples

Example 2: energy release in a fixed target experiment

- "6 GeV protons" (p_B^μ) from the Bevatron hit stationary protons (p_A^μ) in the detector
 - for simplicity we suppress \hat{y} and \hat{z} directions \Rightarrow only two component vectors
- in the **Lab frame** we know all initial quantities:
 - the **four momentum** of the stationary protons: $p_A^\mu = \begin{pmatrix} m_p \\ \vec{0} \end{pmatrix}$
 - the kinetic energy of the accelerated protons $E_B - m_p = 6.5$ GeV
 - through the energy-momentum-mass relation:
 - * the momentum of the accelerated protons $p_B = \sqrt{E_B^2 - m_p^2}$
 - the **total four momentum** in the Lab frame is:
$$P^\mu = p_A^\mu + p_B^\mu = \begin{pmatrix} E_B + m_p \\ \vec{p}_B \end{pmatrix}$$
- in the **CM frame** of the reaction we see the available energy:
 - the momentum of the reaction products is zero $Q^\mu = \begin{pmatrix} E_{CM} \\ \vec{0} \end{pmatrix}$

3. Special Relativity (SR) — Examples

Example 2: energy release in a fixed target experiment ... continued

- How can we connect Lab frame and CM frame ?
 - by a Lorentz transformation (like example 1)
 - by noting that there is an invariant
 - * something that is the same in both frames
- the simplest invariant is the "square" of the total four momentum

$$\begin{aligned} P^2 &= P^\mu P_\mu = (m_p + E_B)^2 - (\vec{p}_B)^2 = m_p^2 + 2m_p E_B + E_B^2 - (\vec{p}_B)^2 \\ &= m_p^2 + 2m_p E_B + m_p^2 = 2m_p(m_p + E_B) \end{aligned}$$

and

$$Q^2 = Q^\mu Q_\mu = (E_{CM})^2 - (\vec{0})^2 = E_{CM}^2$$

- this give the available energy as $E_{CM} = \sqrt{2m_p(m_p + E_B)}$
 - with $m_p = 938 \text{ MeV}$ and $E_B = 7438 \text{ MeV}$ we get $E_{CM} \approx 3964 \text{ MeV} > 4m_p$
 - the Bevatron energy made the reaction possible: $p + p \rightarrow p + p + p + \bar{p}$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Groups — what is a group? (repetition)

- a set G together with a "multiplication \circ " with the properties:
 - for $a, b \in G \Rightarrow c = a \circ b \in G$
 - $(a \circ b) \circ c = a \circ (b \circ c)$
 - $\forall a \in G : \exists e \in G$ with $a \circ e = e \circ a = a$
 - $\forall a \in G : \exists a^{-1} \in G$ with $a \circ a^{-1} = a^{-1} \circ a = e$
- if $a \circ b = b \circ a \forall a, b \in G$: abelian group, otherwise non-abelian
 - abelian: $\{\mathcal{R}, +\}$ or $\{\mathcal{R}^+, \times\}$
 - non-abelian: regular square matrices with the matrix multiplication
- continuous groups: the elements depend on a continuous parameter
 - example: rotations around an axis $R[\theta]$ with $\theta \in [0, 2\pi)$
- Lie group: a continuous group with an analytic multiplication
 - $g[\vec{x}] \circ g[\vec{y}] = g[f(\vec{x}, \vec{y})]$ with $f(\vec{x}, \vec{y})$ analytic in \vec{x} and \vec{y}
 - the unit element is $e = g[\vec{0}]$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Lie groups and Lie algebras

- The $n \times n$ (complex) matrices form representations of Lie groups
- group multiplication is analytic \Rightarrow expansion around unit element
 - unit element $e = \mathbf{1}_{n \times n}$
 - representation $T(g[\alpha]) = \exp[i\alpha_i X_i] \Rightarrow X_k = -i \frac{\partial T(g[\alpha])}{\partial \alpha_k} \Big|_{\vec{\alpha}=0}$
 - generators $\{X_k\}$ span the representation of the Lie group
- the generators $\{X_k\}$ fulfill the Lie algebra $[X_j, X_k] = C_{jk}^\ell X_\ell$
 - with the antisymmetric structure constants $C_{jk}^\ell = -C_{kj}^\ell$
 - rank of the group: number of commuting generators
 - a Casimir operator commutes with all generators $\Rightarrow \propto e$
- the indices i, j, k, ℓ need not indicate single numbers!
 - for the generators we will have $X_i = X_{[mn]} = -X_{[nm]}$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Representations of the Lie group

- using the Jacobi identity

$$\begin{aligned} 0 &= [A, [B, C]] + [B, [C, A]] + [C, [A, B]] \\ &= ABC - ACB - BCA + CBA + BCA - BAC - CAB + ACB + CAB - CBA - ABC + BAC \end{aligned}$$

we get for the structure constants

$$\begin{aligned} 0 &= C_{bc}^d [A, D] + C_{ca}^d [B, D] + C_{ab}^d [C, D] \\ &= C_{bc}^d C_{ad}^e + C_{ca}^d C_{bd}^e + C_{ab}^d C_{cd}^e = -(C_{ca}^d C_{db}^e - C_{cb}^d C_{da}^e) + C_{ab}^d C_{cd}^e \end{aligned}$$

- writing the structure constants as matrices $(M_k)_j^\ell = C_{jk}^\ell$ we have

$$0 = -[(M_a)_c^d (M_b)_d^e - (M_b)_c^d (M_a)_d^e] + C_{ab}^d (M_d)_c^e$$

or

$$[M_a, M_b] = C_{ab}^d M_d$$

⇒ structure constants form the adjoint representation of the Lie group

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Lie Algebra of the rotation group

- a rotation around the \hat{z} -axis by the angle θ is done by the matrix

$$R[\theta] = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix} = e^{i\theta L_z}$$

– in index notation: $R[\theta]^j_k = \cos \theta (\delta_1^j \delta_k^1 + \delta_2^j \delta_k^2) - \sin \theta (\delta_1^j \delta_k^2 - \delta_2^j \delta_k^1) + \delta_3^j \delta_k^3$

- so the generator of the rotations, iL_z , is

$$iL_z = \left. \frac{\partial R[\theta]}{\partial \theta} \right|_{\theta=0} = \begin{pmatrix} -\sin \theta & -\cos \theta & 0 \\ \cos \theta & -\sin \theta & 0 \\ 0 & 0 & 0 \end{pmatrix} \Big|_{\theta=0} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

- and similar

$$iL_x = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \quad iL_y = \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

- these rotations (incl. L_x and L_y) act on 3d column vectors $\vec{v} = \begin{pmatrix} v_x \\ v_y \\ v_z \end{pmatrix}$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Lie Algebra of the rotation group

- with simple matrix multiplication we can see:

$$[iL_x, iL_y] = -iL_z \quad [iL_y, iL_z] = -iL_x \quad [iL_z, iL_x] = -iL_y$$

- or in index notation with $x = 1$, $y = 2$, and $z = 3$: $[L_j, L_k] = i\epsilon_{jkl}L_\ell$

- but there is a **smaller dimensional** realisation of the rotation group!

- using the **Pauli matrices**

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

- one can define the Spin matrices $S_k = \frac{1}{2}\sigma_k$, which give

$$[S_j, S_k] = i\epsilon_{jkl}S_\ell$$

- these Spin matrices act on 2d complex column vectors $\vec{s} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$

with $|\alpha|^2 + |\beta|^2 = 1 \quad \Rightarrow \quad \text{Spinors}$

\Rightarrow **fundamental representation** of the **rotation group** $SU(2)$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Rotations of Spinors

- with simple matrix multiplication we can see for the Pauli matrices:

$$\sigma_x^2 = \sigma_y^2 = \sigma_z^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = 1_{2 \times 2}$$

- So the finite rotation of a spinor around the \hat{y} -axis is

$$\begin{aligned} R[\theta] &= e^{i\theta S_y} = \sum_{n=0}^{\infty} \frac{1}{n!} (i\theta \frac{1}{2} \sigma_y)^n = \sum_{n=2m}^{\infty} \frac{1}{n!} (i\frac{\theta}{2})^n \sigma_y^n + \sum_{n=2m+1}^{\infty} \frac{1}{n!} (i\frac{\theta}{2})^n \sigma_y^n \\ &= \sum_n \frac{(-1)^n (\frac{\theta}{2})^{2n}}{(2n)!} (\sigma_y^2)^n + i \sum_n \frac{(-1)^n (\frac{\theta}{2})^{2n+1}}{(2n+1)!} (\sigma_y^2)^n \sigma_y \\ &= \cos \frac{\theta}{2} * 1_{2 \times 2} + i \sin \frac{\theta}{2} \sigma_y = \begin{pmatrix} \cos \frac{\theta}{2} & -\sin \frac{\theta}{2} \\ \sin \frac{\theta}{2} & \cos \frac{\theta}{2} \end{pmatrix} \end{aligned}$$

- acting on the spinor $\vec{s} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$

⇒ spinors rotate only with **half** of the **rotation angle** θ

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Lorentz transformations (like Galilean transformations)
consist of Boosts and Rotations

- a boost in \hat{x} was done by

$$\Lambda(\eta)^\mu{}_\nu = \cosh \eta (\delta_0^\mu \delta_\nu^0 + \delta_1^\mu \delta_\nu^1) - \sinh \eta (\delta_0^\mu \delta_\nu^1 + \delta_1^\mu \delta_\nu^0) + \delta_2^\mu \delta_\nu^2 + \delta_3^\mu \delta_\nu^3$$

- a rotation between \hat{y} and \hat{z} can be done by

$$\Lambda(\theta)^\mu{}_\nu = \delta_0^\mu \delta_\nu^0 + \delta_1^\mu \delta_\nu^1 + \cos \theta (\delta_2^\mu \delta_\nu^2 + \delta_3^\mu \delta_\nu^3) - \sin \theta (\delta_2^\mu \delta_\nu^3 - \delta_3^\mu \delta_\nu^2)$$

- we obtain the generators for boosts with $-i \frac{\partial \Lambda(\eta)^\mu{}_\nu}{\partial \eta} \Big|_{\eta=0} =$

$$-i \sinh \eta (\delta_0^\mu \delta_\nu^0 + \delta_1^\mu \delta_\nu^1) + i \cosh \eta (\delta_0^\mu \delta_\nu^1 + \delta_1^\mu \delta_\nu^0) \Big|_{\eta=0} = i (\delta_0^\mu \delta_\nu^1 + \delta_1^\mu \delta_\nu^0)$$

- we obtain the generators for rotations with $-i \frac{\partial \Lambda(\theta)^\mu{}_\nu}{\partial \theta} \Big|_{\theta=0} =$

$$+i \sin \theta (\delta_2^\mu \delta_\nu^2 + \delta_3^\mu \delta_\nu^3) + i \cos \theta (\delta_2^\mu \delta_\nu^3 - \delta_3^\mu \delta_\nu^2) \Big|_{\theta=0} = i (\delta_2^\mu \delta_\nu^3 - \delta_3^\mu \delta_\nu^2)$$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Boosts and Rotations ... continued

- The other **boosts** go in \hat{y} or \hat{z} direction: $i(\delta_0^\mu \delta_\nu^i + \delta_i^\mu \delta_\nu^0)$,
or with the **indices $0i$ down**: $(M_{0i})^\mu{}_\nu = i(\delta_0^\mu (-g_{i\nu}) + \delta_i^\mu g_{0\nu})$
- The other **rotations** go in $\hat{x}\hat{y}$ or $\hat{x}\hat{z}$ direction: $i(\delta_j^\mu \delta_\nu^k - \delta_k^\mu \delta_\nu^j)$,
or with the **indices jk down**: $(M_{jk})^\mu{}_\nu = i(\delta_j^\mu (-g_{k\nu}) - \delta_k^\mu (-g_{j\nu}))$
- both generators have now the same form:

$$(M_{\alpha\beta})^\mu{}_\nu = -i(\delta_\alpha^\mu g_{\beta\nu} - \delta_\beta^\mu g_{\alpha\nu})$$

- with $\omega^{\alpha\beta} = -\omega^{\beta\alpha}$ we get

$$\Lambda(\omega)^\mu{}_\nu = \exp[i(M_{\alpha\beta}\omega^{\alpha\beta})^\mu{}_\nu] = \exp[(\delta_\alpha^\mu g_{\beta\nu} - \delta_\beta^\mu g_{\alpha\nu})\omega^{\alpha\beta}]$$

- How to understand / use this formula? ... How to get a matrix?
 1. pick the indices of $\omega^{\alpha\beta}$: ω^{0i} (ω^{jk}) for a boost (rotation) in \hat{i} - ($\hat{j}\hat{k}$ -) direction
 2. write the matrix $\delta_\alpha^\mu g_{\beta\nu} - \delta_\beta^\mu g_{\alpha\nu}$ with row-(column-) number μ (ν)
 - * it will only have two non-zero entries
 3. squaring the matrix gives a diagonal matrix with only two equal entries
 4. the powerseries expansion gives you the expected boost / rotation

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Generators for the Lorentz transformations

- these generators fulfill the Lie algebra of the Lorentz group:

$$[M_{\alpha\beta}, M_{\gamma\delta}]^{\mu\nu} = i(g_{\alpha\gamma}M_{\beta\delta} - g_{\beta\gamma}M_{\alpha\delta} - g_{\alpha\delta}M_{\beta\gamma} + g_{\beta\delta}M_{\alpha\gamma})^{\mu\nu}$$

- unifying time and spatial translations $P_\mu = (H, P_i)$
- we get the rest of the Poincaré algebra:

$$[P_\mu, P_\nu] = 0 \quad \text{and} \quad [M_{\alpha\beta}, P_\mu] = i(g_{\alpha\mu}P_\beta - g_{\beta\mu}P_\alpha)$$

- the generators of the Poincaré group are: P_μ and $M_{\alpha\beta}$
 - all rotations, boosts, and translations are elements of the Poincaré group

Invariants of the Poincaré group

- are objects that commute with all elements of the Poincaré group
 - it is enough to check if they commute with the generators ...

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Invariants of the Poincaré group

- obviously $[ab, c] = a[b, c] + [a, c]b = abc - acb + acb - cab = abc - cab$
- so $[P_\mu, P^2] = [P_\mu, P_\nu]P^\nu + P^\nu[P_\mu, P_\nu] = 0$
- and $[M_{\alpha\beta}, P^2] = g^{\mu\nu}[M_{\alpha\beta}, P_\mu]P_\nu + g^{\mu\nu}P_\mu[M_{\alpha\beta}, P_\nu]$
 $= g^{\mu\nu}i(g_{\alpha\mu}P_\beta - g_{\beta\mu}P_\alpha)P_\nu + g^{\mu\nu}P_\mu i(g_{\alpha\nu}P_\beta - g_{\beta\nu}P_\alpha)$
 $= -2i[P_\alpha, P_\beta] = 0$.

$\Rightarrow P^2 = m^2$ invariant is a consequence of the Poincaré algebra!

- Another invariant is W^2
 - with the Pauli-Lubanski vector $W^\mu = \frac{1}{2}\epsilon^{\mu\nu\rho\lambda}M_{\nu\rho}P_\lambda$
 $[P_\kappa, W^\mu] = \frac{1}{2}\epsilon^{\mu\nu\rho\lambda}([P_\kappa, M_{\nu\rho}]P_\lambda + M_{\nu\rho}[P_\kappa, P_\lambda])$
 $= \frac{1}{2}\epsilon^{\mu\nu\rho\lambda}i(g_{\rho\kappa}P_\nu - g_{\nu\kappa}P_\rho)P_\lambda = 0 \quad \Rightarrow \quad [P_\kappa, W^2] = 0$
 - $0 = [M_{\alpha\beta}, W^2]$ is true, but checking is too difficult ...

\Rightarrow Particles can be characterised by the eigenvalues of P^2 and W^2

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Eigenvalues of P^2 and W^2

- the spin vector W^μ is orthogonal to P_μ :

$$(P.W) = P^\mu \frac{1}{2} \epsilon_{\mu\nu\rho\lambda} M^{\nu\rho} P^\lambda = 0$$

- For a particle at rest: $P_\mu = (m, 0)$

- $P^2 = m^2 \Rightarrow$ the **eigenvalue** of P^2 is m^2

- $W_\mu = \frac{1}{2} m \epsilon_{\mu\nu\rho 0} M^{\nu\rho} = m(0, \vec{J})$

- so $W^2 = m^2(0^2 - \vec{J}^2) = -m^2 \vec{J}^2 \rightarrow -m^2 s(s+1)$

\Rightarrow the **eigenvalue** of W^2 is $m^2 s(s+1)$

- For a massless particle $P_\mu = (\eta, \eta, 0, 0)$

- we have $P^2 = (P.W) = W^2 = 0$

\Rightarrow the **eigenvalues** of P^2 and W^2 are 0

- we can construct the operator $O = \lambda^2 P^2 - 2\lambda(P.W) + W^2 = (\lambda P - W)^2$

- * where λ depends on the representation (i.e. the **spin**) of the particle

- we get: $W^\mu = \lambda P^\mu$ with the **helicity** $\lambda = 0, \pm\frac{1}{2}, \pm 1, \dots$

\Rightarrow Particles are characterised by **mass** and **spin** !

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

Investigating the Lorentz group

- distinguishing again boosts and rotations

$$K_i = M_{0i} = -M^{0i} \quad \text{and} \quad J_i = \frac{1}{2}\epsilon_{ijk}M^{jk} ,$$

the Lorentz algebra gives

$$[J_j, J_k] = i\epsilon_{jkl}J_l , \quad [K_j, K_k] = -i\epsilon_{jkl}J_l , \quad [J_j, K_k] = i\epsilon_{jkl}K_l$$

- defining

$$L_i = N_i = \frac{1}{2}(J_i + iK_i) \quad \text{and} \quad R_i = N_i^\dagger = \frac{1}{2}(J_i - iK_i)$$

one gets

$$[L_j, R_k] = 0 , \quad [L_j, L_k] = i\epsilon_{jkl}L_l , \quad [R_j, R_k] = i\epsilon_{jkl}R_l$$

⇒ the Lorentz algebra is similar to $SU(2)_L \otimes SU(2)_R$!

- it has two invariants: $L_i L_i = n(n + 1)$ and $R_i R_i = m(m + 1)$
 - the angular momentum is $J_i = L_i + R_i \Rightarrow \text{spin } j = n + m$

3. Special Relativity (SR) — Algebra of the Poincaré group (optional)

classifying particles

- according to the eigenstates (n, m) of $SU(2)_L \otimes SU(2)_R$
 - $(0, 0)$ is a scalar
 - $(\frac{1}{2}, 0)$ is the χ_α left-handed Weyl-spinor
 - $(0, \frac{1}{2})$ is the $\bar{\eta}^{\dot{\alpha}}$ right-handed Weyl-spinor
 - $(\frac{1}{2}, 0) \oplus (0, \frac{1}{2})$ is $\Psi = \begin{pmatrix} \chi_\alpha \\ \bar{\eta}^{\dot{\alpha}} \end{pmatrix}$, the Dirac-spinor
 - $(\frac{1}{2}, 0) \otimes (0, \frac{1}{2}) = (\frac{1}{2}, \frac{1}{2})$ is $(\chi \sigma^\mu \bar{\eta}) = \chi^\alpha \sigma_{\alpha\dot{\alpha}}^\mu \bar{\eta}^{\dot{\alpha}}$, a **spin-1 four-vector**

⇒ in that sense is the **spinor** the **square root** of the **vector**

- under Parity: $J_i \xrightarrow{P} J_i, K_i \xrightarrow{P} -K_i, \Rightarrow L_i \xrightarrow{P} R_i, (n, m) \xrightarrow{P} (m, n)$
 - the scalar stays the same
 - $(\frac{1}{2}, 0) \xrightarrow{P} (0, \frac{1}{2})$, therefore $\chi_\alpha \xrightarrow{P} \bar{\eta}^{\dot{\alpha}}$
 - $(\frac{1}{2}, 0) \oplus (0, \frac{1}{2}) \xrightarrow{P} (0, \frac{1}{2}) \oplus (\frac{1}{2}, 0) = (\frac{1}{2}, 0) \oplus (0, \frac{1}{2})$
 - ⇒ so a **Dirac-spinor** stays a **Dirac-spinor**
 - the four-vector stays the same