

Plasma physics seminar 2023 11 17  
 Chapter 3  
 Single particle motions

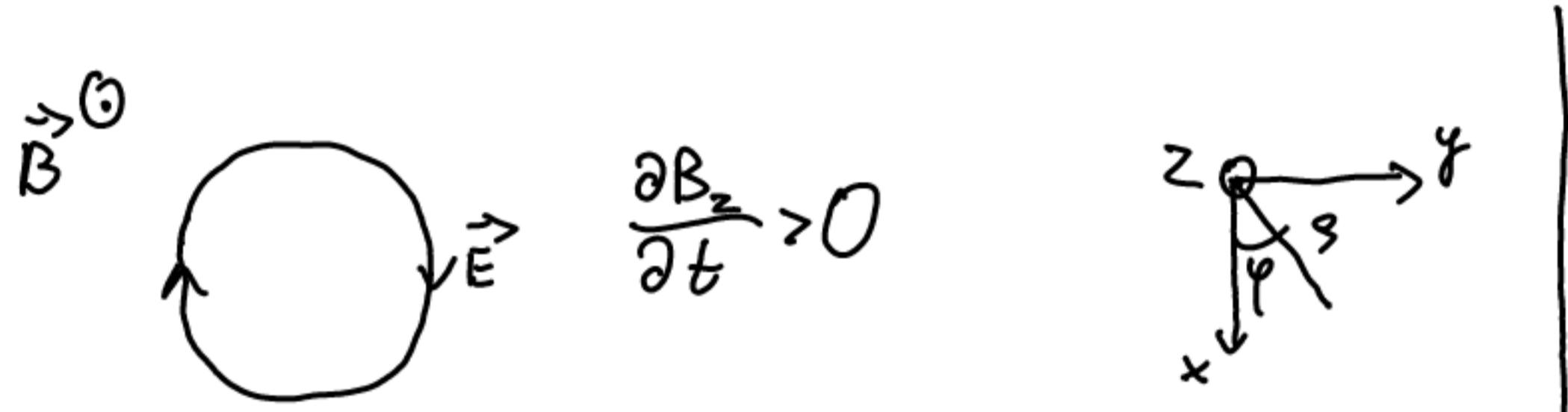
### 3.5 Motion in a Time Varying Magnetic Field

For a time varying field, Faraday's law applies

$$[\nabla \times \vec{E}] = -\frac{\partial \vec{B}}{\partial t}$$

In this case the LHS must also be non zero, thus the electric field cannot be expressed as a gradient of a potential. Thus we have a non-conservative electric field and the total energy of the particle is not constant.

Let us consider a uniform magnetic field that is varying much more slowly than the cyclotron period.



$$\oint_C \vec{E} \cdot d\vec{l} = - \frac{d}{dt} \oint_S \vec{B} \cdot d\vec{A} \Rightarrow \oint_C \vec{E} \cdot d\vec{l} < 0 \quad \begin{cases} \text{if } d\vec{l} \text{ is directed counterclockwise} \\ \text{then } \vec{E} \text{ is directed clockwise.} \end{cases}$$

A charged particle in this field gains energy per orbit | For +q C is clockwise  
 $\Delta w_+ = q \oint_C \vec{E} \cdot d\vec{l} = -q \oint_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$  | for -q C is counterclockwise

Here positive sense of C is in the direction of the particle motion. |  $d\vec{A}$  changes direction

Assuming slowly varying fields and  $A \approx \pi r_c^2$  we get

$$\Delta w_+ = |q| \frac{dB}{dt} \cdot \pi r_c^2$$

Cyclotron period is  $\Delta t = \frac{2\pi}{\omega_c}$ .

Thus

$$\frac{dw_+}{dt} = \frac{1}{2\pi} \omega_c |q| g / \frac{dB}{dt} \pi g_c^2$$

We had one of the expressions for the magnetic moment

$$\mu = \frac{|q|}{2} \omega_c g_c^2$$

Therefore

$$\frac{dw_+}{dt} = \mu \frac{dB}{dt} \Rightarrow \mu = \frac{w_+}{B} \Rightarrow \frac{dw_+}{dt} = \frac{w_+}{B} \frac{dB}{dt} \Rightarrow \frac{dw_+}{w_+} = \frac{dB}{B}$$

$$\Rightarrow \ln w_+ = \ln B + \ln C \Rightarrow \frac{w_+}{B} = C = \text{const}$$

For a time-dependent magnetic field the magnetic moment is constant.

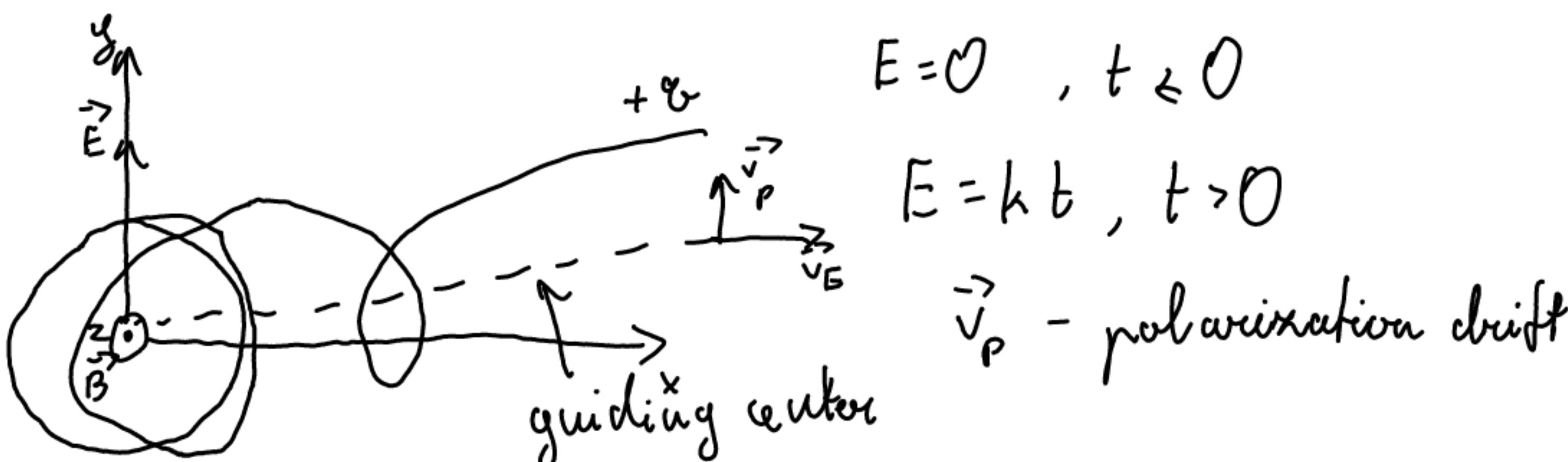
By a change of coordinates the motion in a converging magnetic field can be converted to a time-dependent magnetic field. (In both cases  $\mu = \text{const}$ )

The conservation of the magnetic moment is equivalent to maintaining a constant magnetic flux through the cyclotron orbit.

$$\mu = \frac{|q|}{2} \omega_c g_c^2 = \left[ \omega_c = \frac{|q| B}{m} \right] = \frac{q^2}{2m} B g_c^2 = \frac{1}{2\pi} \frac{q^2}{m} \Phi_B \text{ with } \Phi_B = B \cdot \pi g_c^2$$

### 3.6 Polarization drift

If  $\vec{E} = \vec{E}(t)$  in a  $[\vec{E} \times \vec{B}]$  field geometry, then there is an additional drift in the direction of  $\frac{d\vec{E}}{dt}$ . For positive charges this is in the direction of  $\frac{d\vec{E}}{dt}$ , for negative charges - in the opposite direction. Therefore this drift causes a change of polarization and is thus called the polarization drift.



We will now assume that  $\frac{d\vec{E}}{dt}$  is very small.

- Two time-scales : 1) rapid time-scale associated with the cyclotron motion ;  
 2) very slow time-scale associated with the electric field and polarization drifts.

We start with the Lorentz force equation

$$m \frac{d\vec{v}}{dt} = q \vec{E} + q [\vec{v} \times \vec{B}] \quad (1)$$

We will obtain the drift velocity at the guiding center by averaging the perpendicular velocity,  $\langle \vec{v}_\perp \rangle$ .

We multiply (1)  $\times \frac{\vec{B}}{qB^2}$ :

$$\frac{m}{qB^2} \frac{d}{dt} [\vec{v} \times \vec{B}] = \underbrace{\frac{[\vec{E} \times \vec{B}]}{B^2}}_{\vec{v}_E} - \frac{1}{B^2} \underbrace{[\vec{B} \times [\vec{v} \times \vec{B}]]}_{\vec{v} B^2 - \vec{B}(\vec{B} \cdot \vec{v})}$$

The parallel velocity is  $\vec{v}_\parallel = \frac{\vec{B}(\vec{v} \cdot \vec{B})}{B^2}$ . We also have  $\vec{v} - \vec{v}_\parallel = \vec{v}_\perp$ . Thus

$$\frac{m}{qB^2} \frac{d}{dt} [\vec{v} \times \vec{B}] = \vec{v}_E - \vec{v}_\perp \Rightarrow \vec{v}_\perp = \vec{v}_E - \frac{m}{qB^2} \frac{d}{dt} [\vec{v} \times \vec{B}]$$

We compute the drift velocity by averaging  $\langle \vec{v}_\perp \rangle$  over one orbit. Since the cyclotron motion is very fast  $\vec{E}$  is constant in the average. Therefore,

$$\vec{v}_d = \langle \vec{v}_\perp \rangle = \vec{v}_E - \frac{m}{qB^2} \cdot \left[ \langle \frac{d\vec{v}}{dt} \rangle \times \vec{B} \right]$$

$$\langle \frac{d\vec{v}}{dt} \rangle = \frac{q}{m} \vec{E} + \frac{q}{m} [\langle \vec{v} \rangle \times \vec{B}],$$

This is confusing. Apparently, we should assume

$$1) \langle \frac{d\vec{v}}{dt} \rangle = \frac{d}{dt} \langle \vec{v} \rangle \quad , \text{ not sure about this}$$

$$2) \langle \vec{v} \rangle \times \vec{B} = -\vec{E} \quad , \text{ would only make sense if } \langle \frac{d\vec{v}}{dt} \rangle = 0$$

We should obtain

$$\vec{v}_d = \vec{v}_E + \underbrace{\frac{m}{qB^2} \frac{d\vec{E}}{dt}}_{\vec{v}_P}$$

$\vec{v}_P$  polarization drift, depends on the sign of the charge.

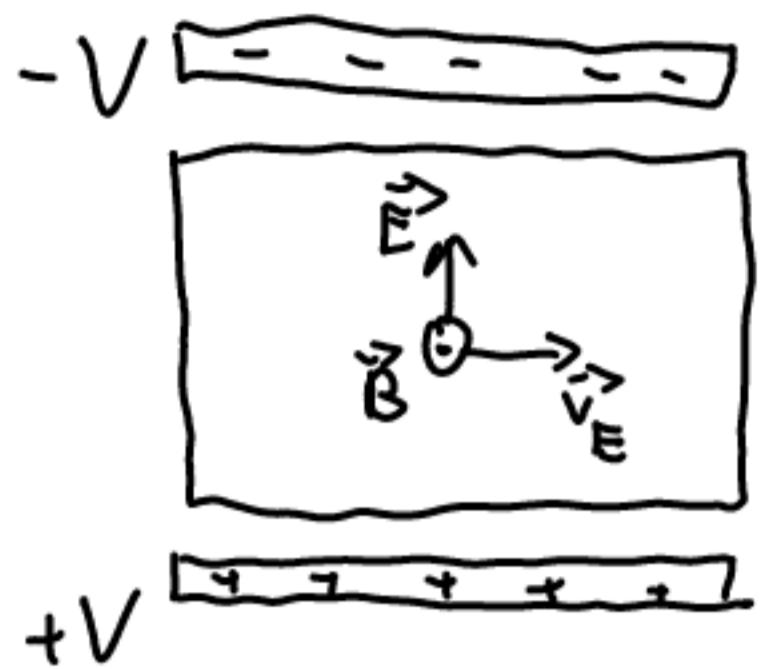
Polarization drift produces a current:

$$\vec{j}_P = \frac{n_0(m_e + m_i)}{B^2} \frac{d\vec{E}}{dt} \Rightarrow \text{dominated by ions.}$$

Now we would like to compare the charge polarization caused by the polarization drift to the charge polarization that develops when an electric field is applied to a solid dielectric material. In the latter case

$$\vec{D} = \epsilon_0 K \vec{E}$$

We consider plasma placed between the plates of a capacitor



We gradually increase the electric field from zero to some final value by changing the voltage.

$\vec{j}_p$  is produced due to the time varying electric field  
A surface charge density  $\sigma_p = \int dt \vec{j}_p \cdot \hat{n}$  develops.

Apparently

$$\vec{P} \cdot \hat{n} = \sigma_p \Rightarrow \int dt \vec{j}_p \cdot \hat{n} = \int dt \frac{n_0(m_e + m_i)}{B^2} \frac{d\vec{E}}{dt} \cdot \hat{n} = \frac{n_0(m_e + m_i)}{B^2} \vec{E} \cdot \hat{n}$$

Therefore

$$\vec{P} = \epsilon_0 \underbrace{\left[ \frac{n_0(m_e + m_i)}{\epsilon_0 B^2} \right]}_{\chi} \vec{E}$$

$\chi$  - dielectric susceptibility

Finally,

$$K = 1 + \gamma = 1 + \frac{n_0(m_e + m_i)}{\epsilon_0 B^2}$$

We should later see that this dielectric constant accounts for some specific waves in a plasma.